

Vorlesungen Mechatronik im Wintersemester

Energiforsk Seminar: Lectures in the Power Plants Ringhals, Oskarshamn and Forsmark, March 2022



TECHNISCHE
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Vibrations of Turbines and Generators in Power Plants

Lecture IV **Vibrations in Generators of Turbogenerators**

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Vibrations in Generators of Turbogenerators

- **Some Vibration Problems in Generators**
- **End Winding Vibrations in Generators**
- **Lateral Vibrations due to Time Variant Stiffness of the Generator Shaft**
- **Sub Synchronous Resonance (SSR)**

Some Vibration Problems in Generators

Turbogenerator System with Components



Generator

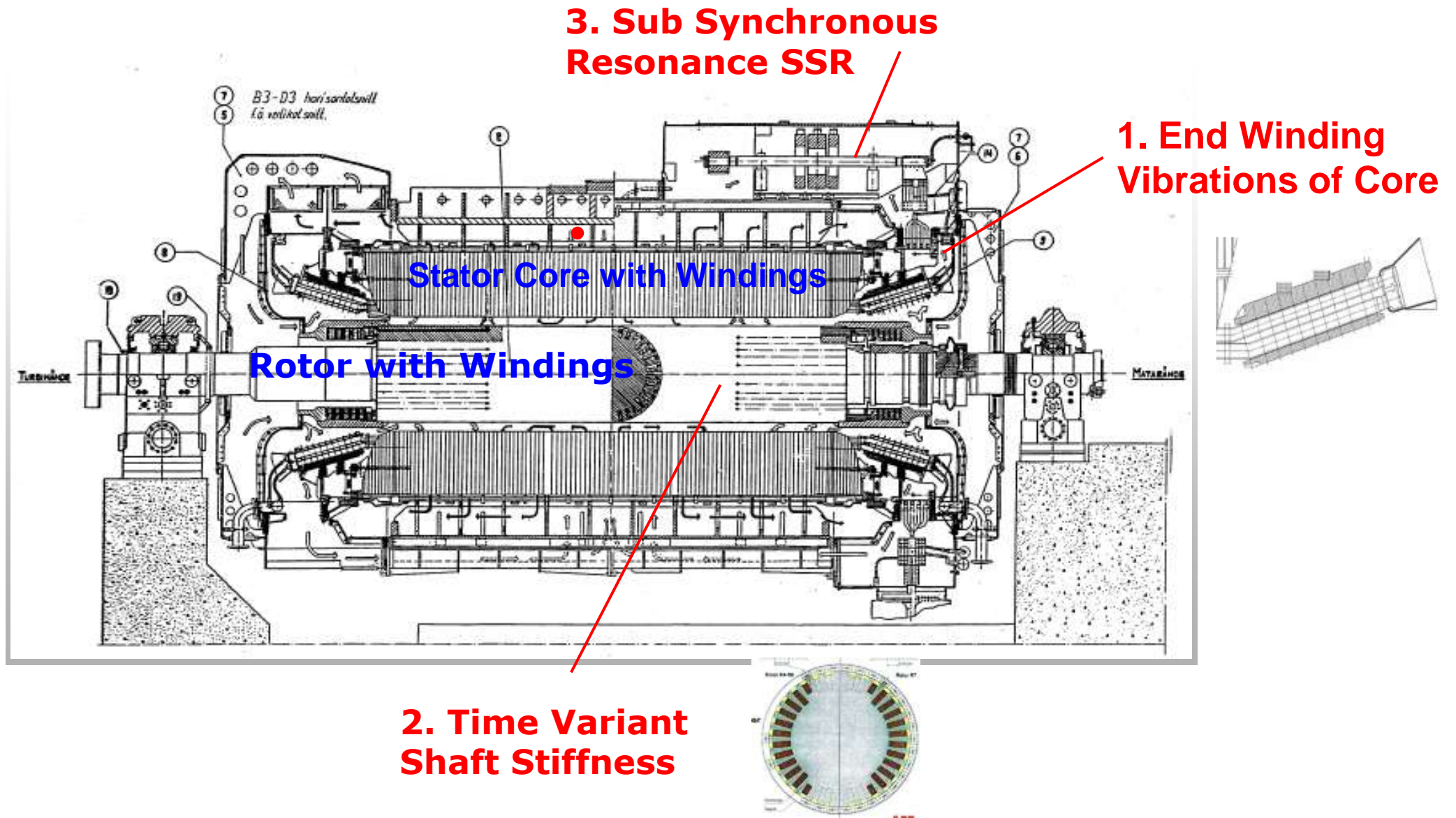
Pipe System

Low Pressure Turbines LPT

High Pressure Turbine HPT

Some Vibration Problems in Generators

Generator Cross Section with Rotor and Stator Core

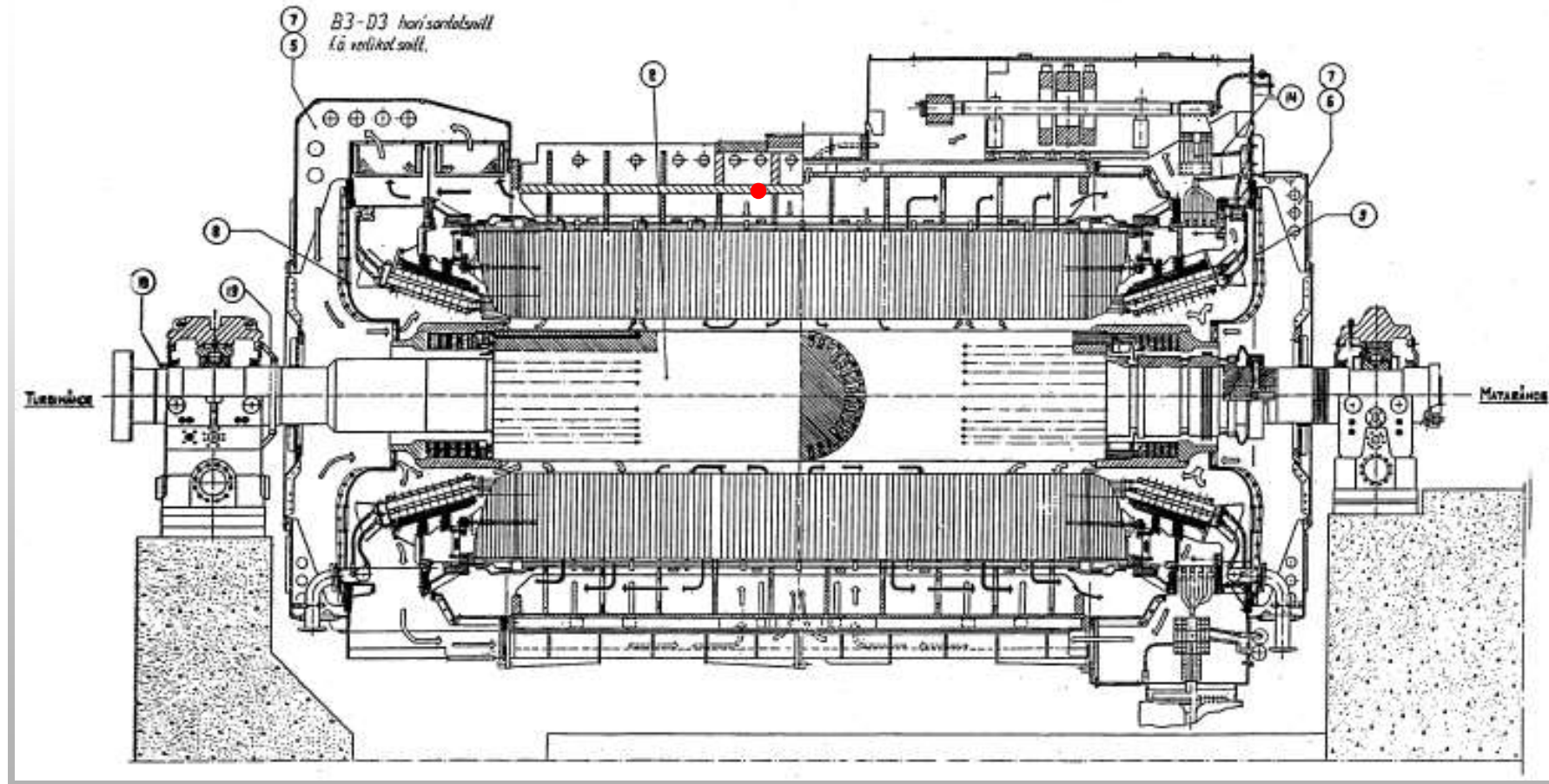


Vibrations in Generators of Turbogenerators

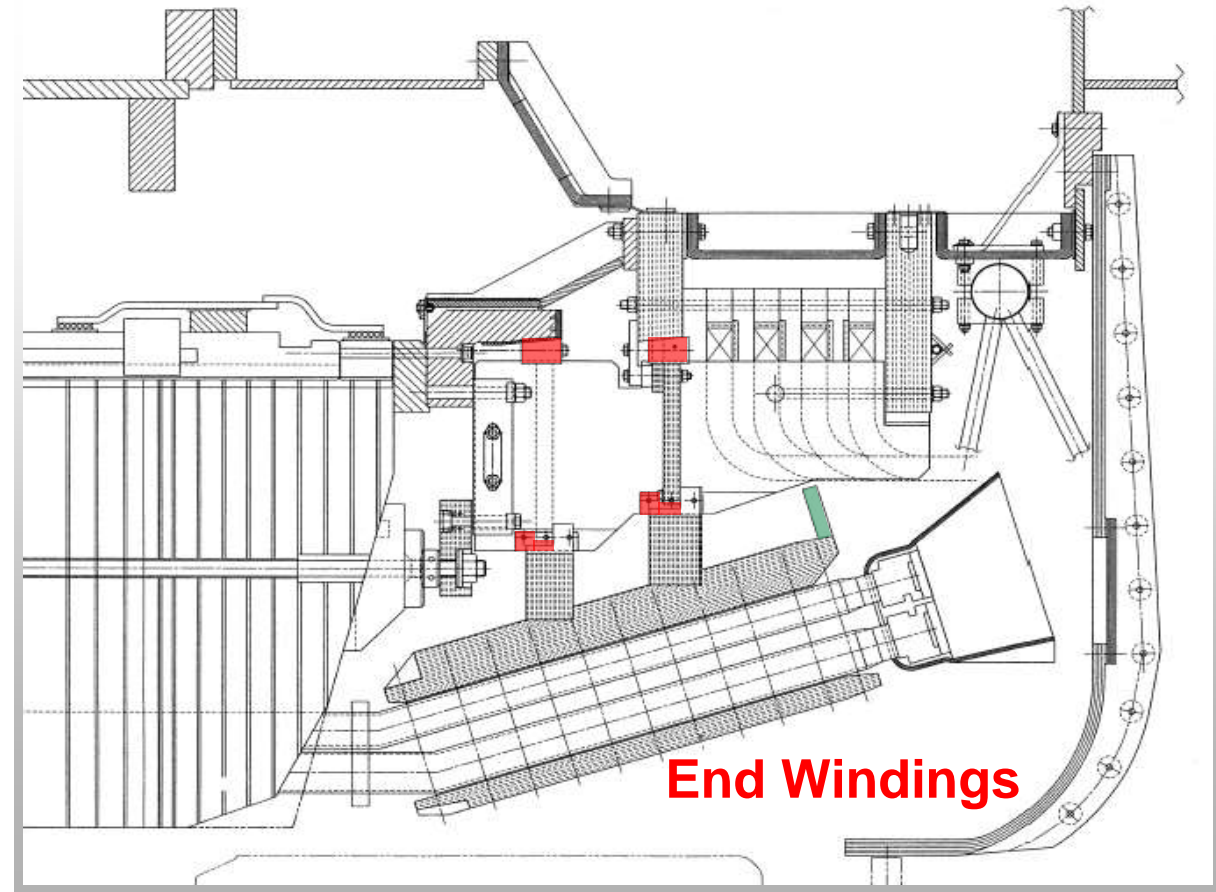
- **Special Vibration Problems in Generators**
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End Winding Vibrations in Generators

Generator Cross Section

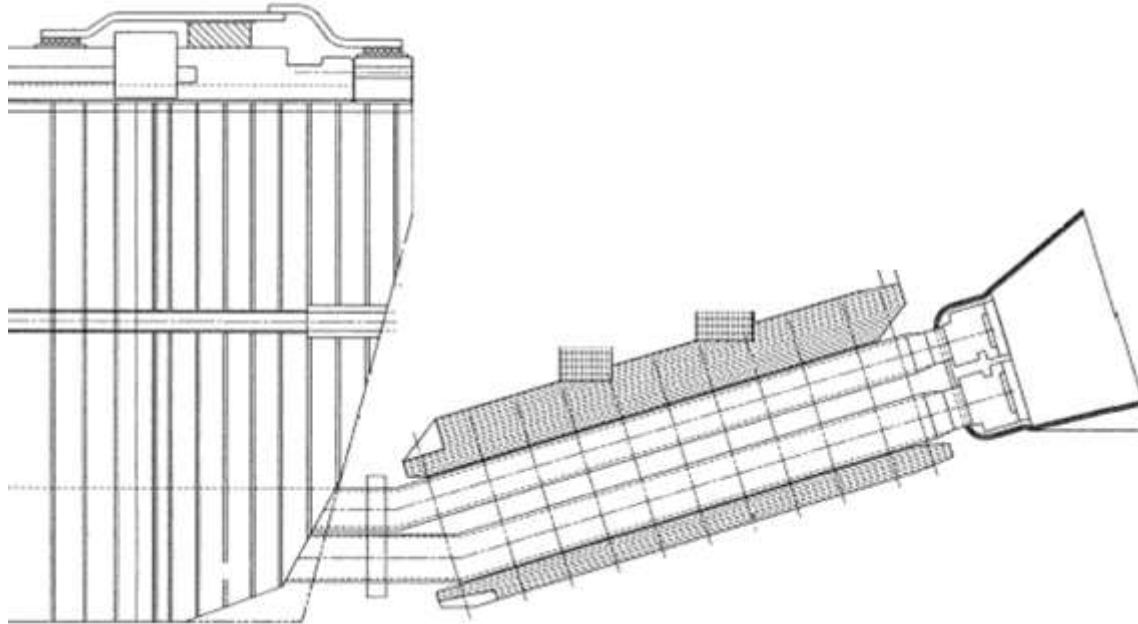


- **End Winding Vibrations** have been one of the problems in generators
- They are excited **at 100 Hz** by Electro-Magnetic forces and amplified due to **resonances close to 100 Hz**
- The **mode shape** has often an **elliptical form**



Concepts: **End Windings have supports**

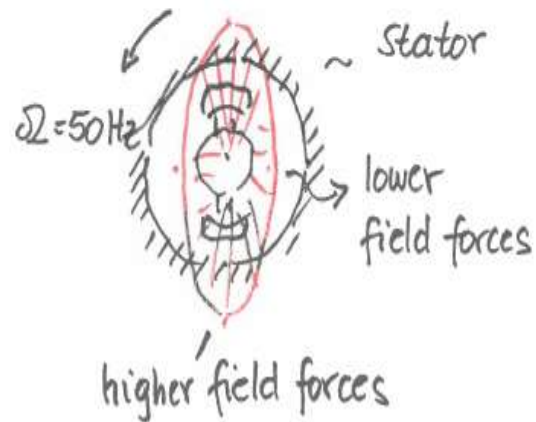
or are designed as **Free End Windings**



- **Free Endwinding Solution**
- **Resonance behavior:**
- **Short circuit: safety, stress analysis**

Excitation of Generator Stator Vibration

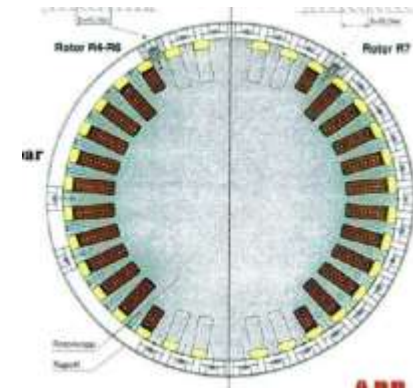
The excitation of the generator stator is coming from the rotating magnetic field. Due to the fact, that the elliptical



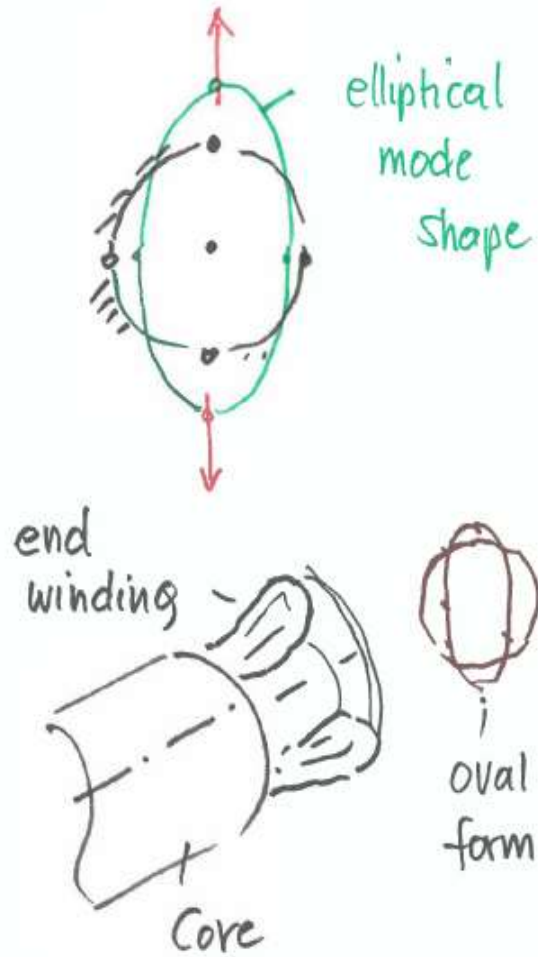
force field is rotating with $\omega = 50 \text{ Hz}$,

the stator is excited by the double rotational frequency $2\omega \approx 100 \text{ Hz}$

What kind of modes can be excited by this 2ω (100 Hz) excitation.



Rotor with rotating **Magnetic Field** in a Two Pole Generator



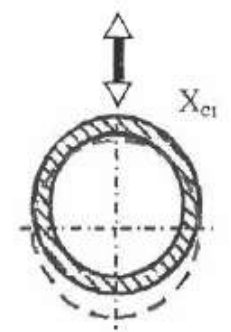
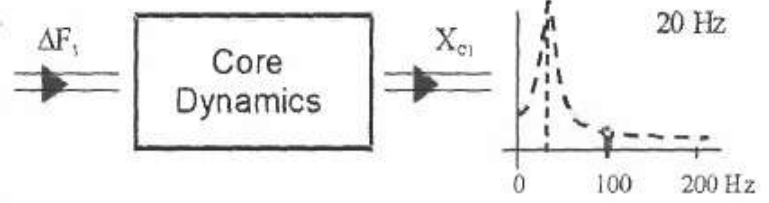
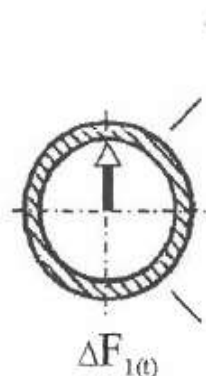
The natural frequency of the core with an elliptical mode ~~is~~ has been calculated at a frequency of 190 Hz. This is far away from 100 Hz excitation and there should be no problem.

However, the question arises, whether the end windings can also be excited by 100 Hz frequency on both sides of the stator. In the measurement results we see a very clear oval mode shape.

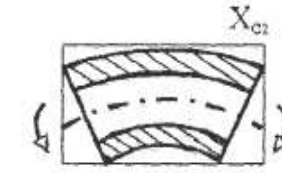
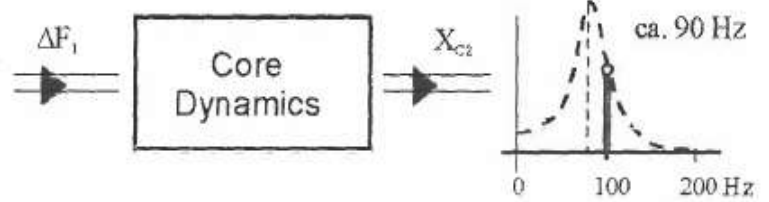
Excitation

Frequency Response - Output

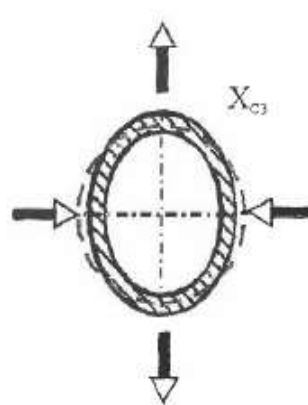
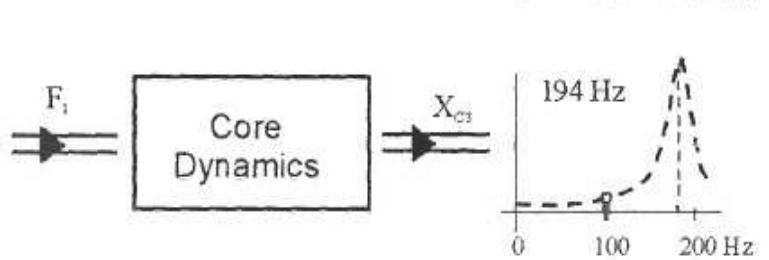
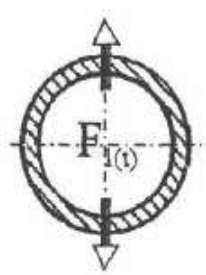
Vibration Mode and Frequency



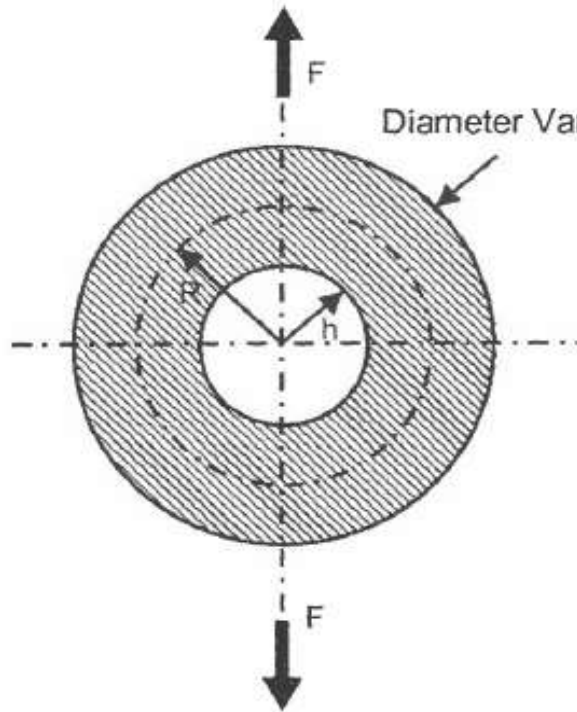
Rigid Body Mode of the Core
Frequency: 20 Hz



Bending Mode (Banana) of Core
Frequency: ca. 90 Hz



Ovalization of the Core
Frequency: ca. 194 Hz



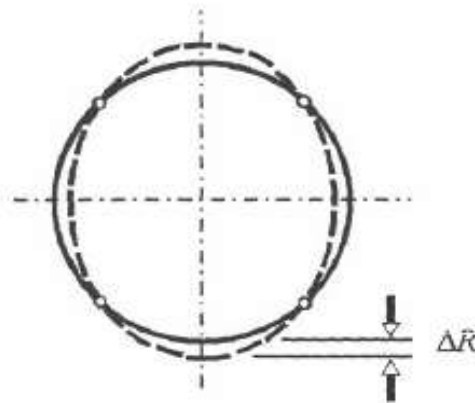
$$\Delta D = 0,148 \frac{FR^3}{EJ}$$

$$\Delta D_{stat} = 8,05 \mu m$$

$$\Delta R_{stat} = 4,02 \mu m$$

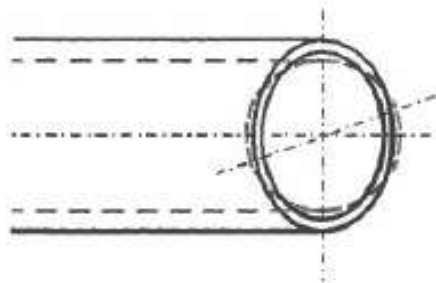
$$\Delta R_{dyn} \approx 1,25 * \Delta R_{stat} = 5 \mu m$$

Force: $F = 2370 \text{ kN}$
 Radius: $R = 1,2 \text{ m}$
 Thickness: $h = 0,9 \text{ m}$
 E-Modul: $E = 2,1 * 10^{11} \text{ N/m}^2$
 Moment of Inertia: $J = Lh^3/12$
 Length $L = 5,9 \text{ m}$

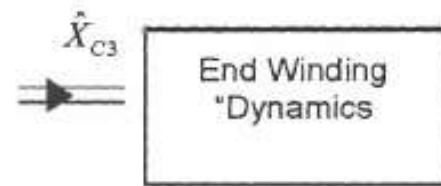


Core Deformation due to a **Static Load**

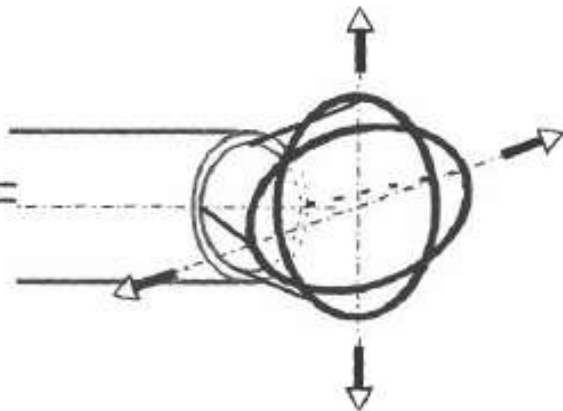
"Excitation" due to
Core Ovalization $X_{C3}(t)$ - 100 Hz



This core ovalization
is well suited to excite
the ovalization of the
End Windings

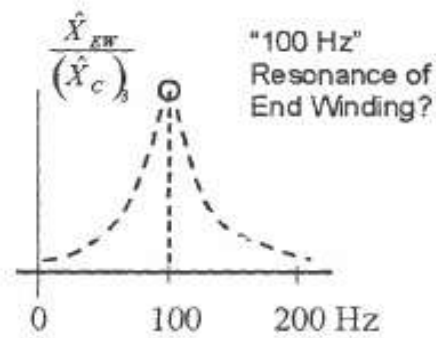


"Vibration Response" of
End Windings is an
"Ovalization". Oval form
rotates with 100 Hz



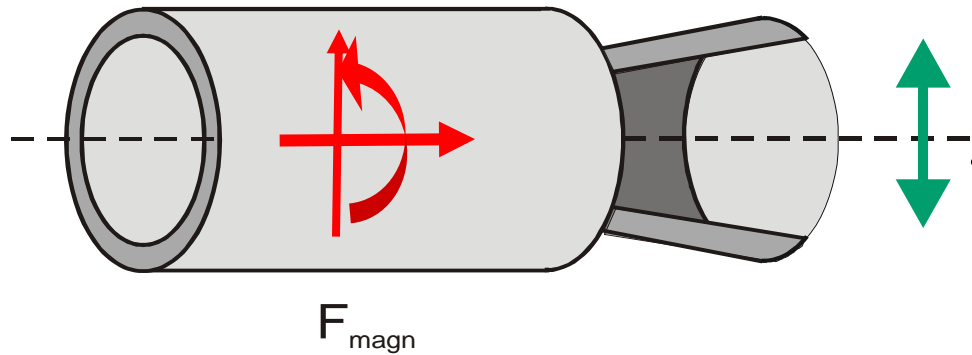
Ovalization was identified
during operation.

$$\frac{\hat{Y}_{EW}}{(\hat{X}_c)_3} = 10 \quad \text{Resonance!}$$

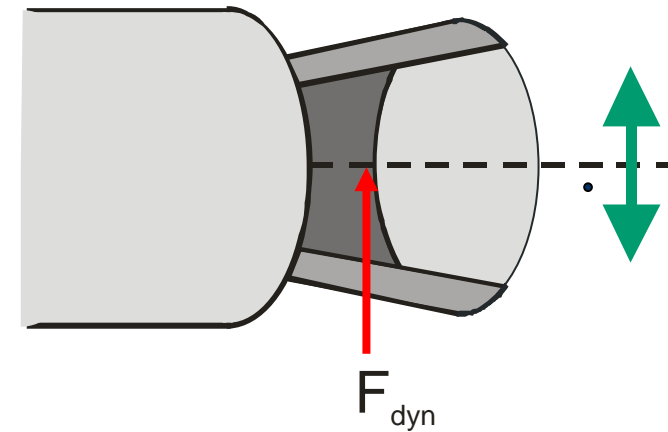


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- There are two ways to **excite** the **End Winding Vibrations**

Indirect Excitation via Magnetic Forces and the the Core

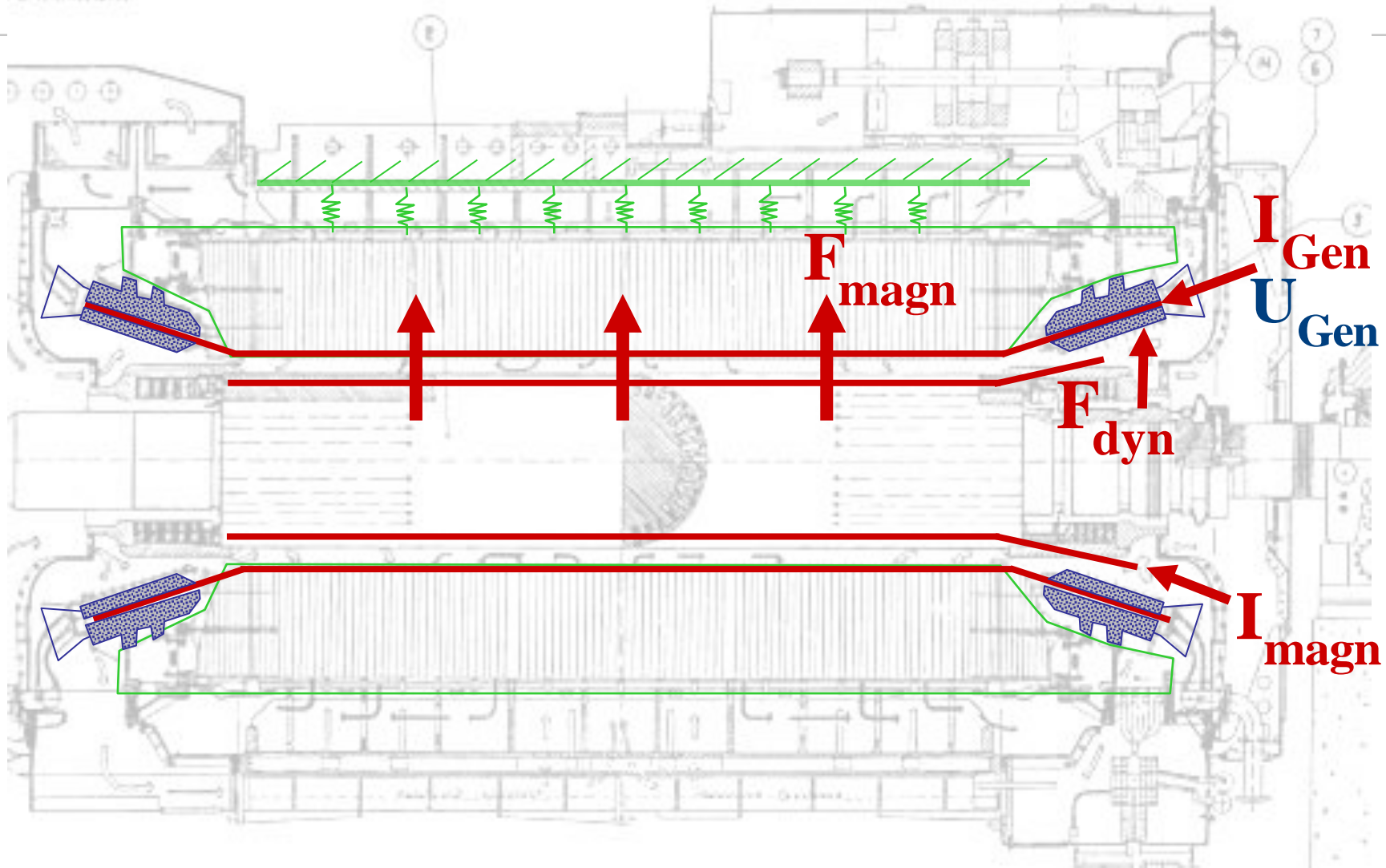


Direct Excitation due to currents



T (Turbine)

M (Exiter)



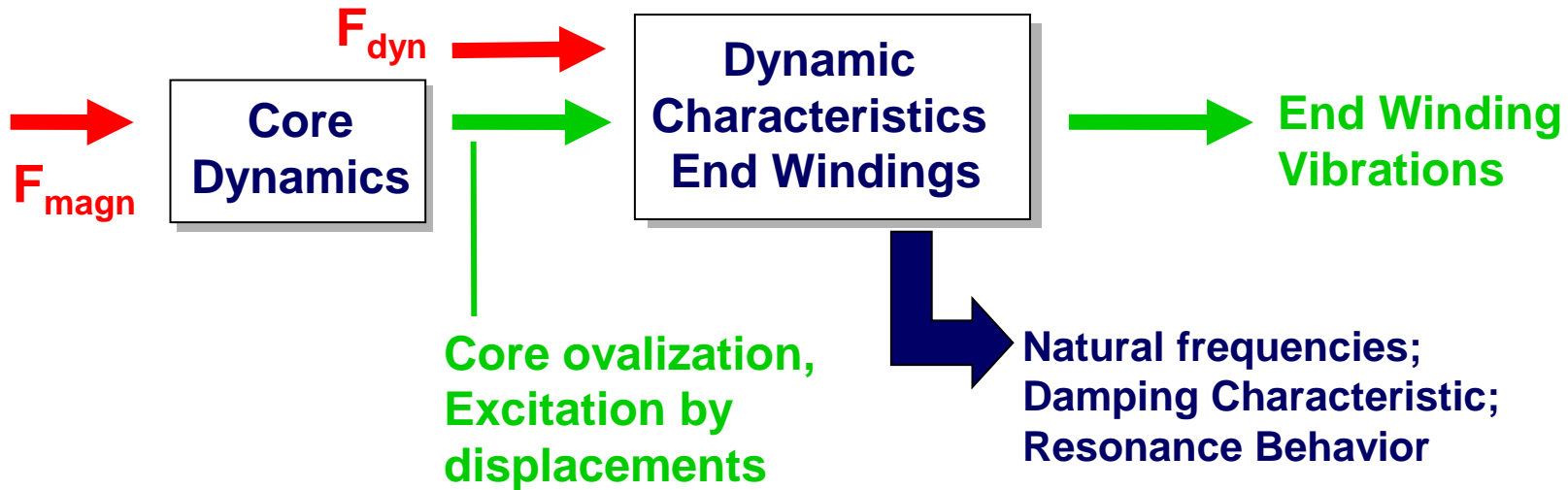
End Winding Vibrations

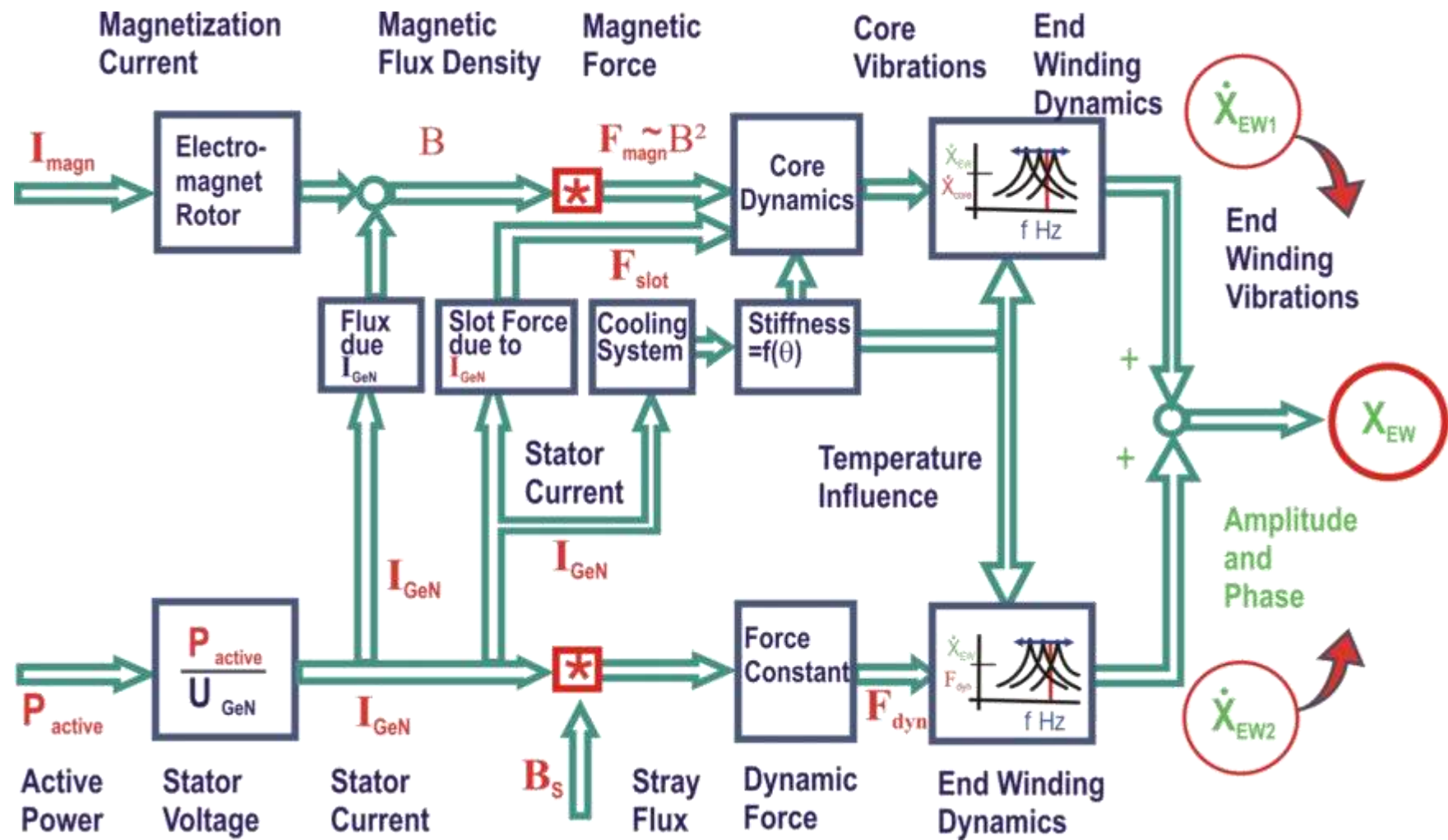
depend on

Electrodynamic
Force F_{dyn}

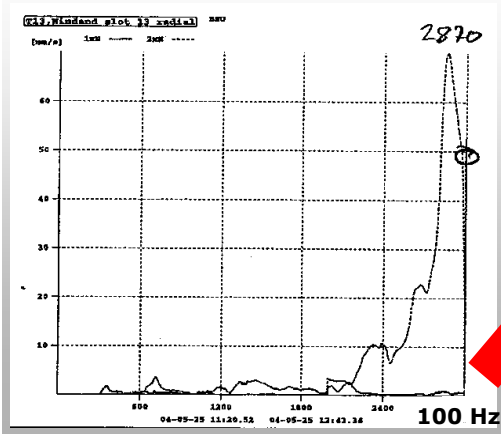
Electromagnetic
Forces F_{magn}

Dynamic Characteristics
of End Windings

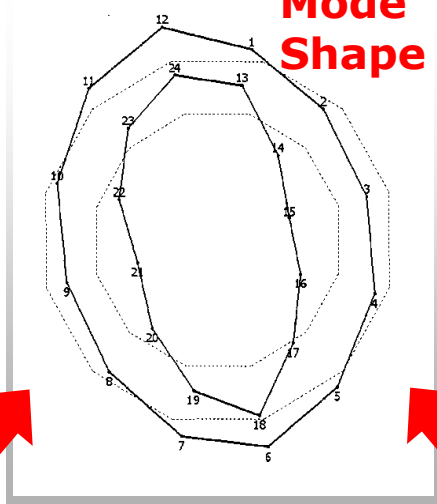




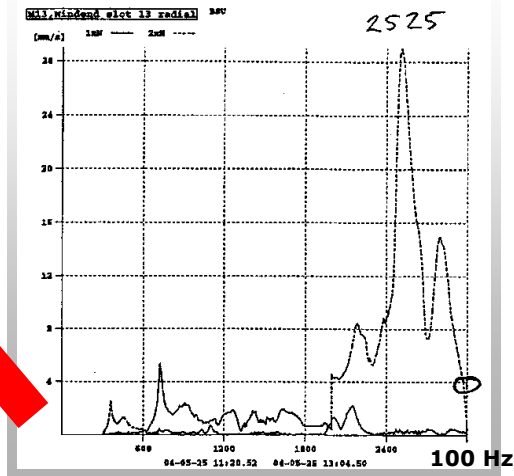
Resonance Turbine Side



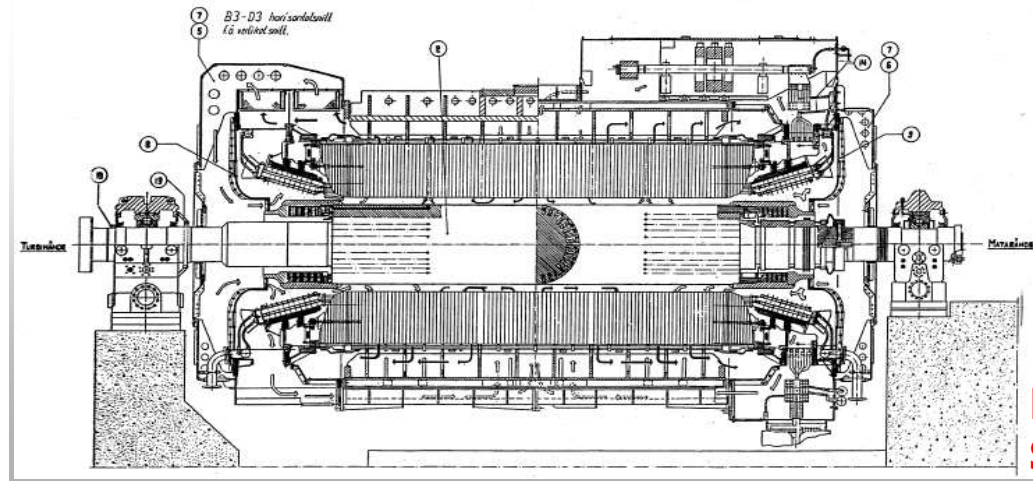
Mode Shape



Resonance Exciter Side



Turbine Side

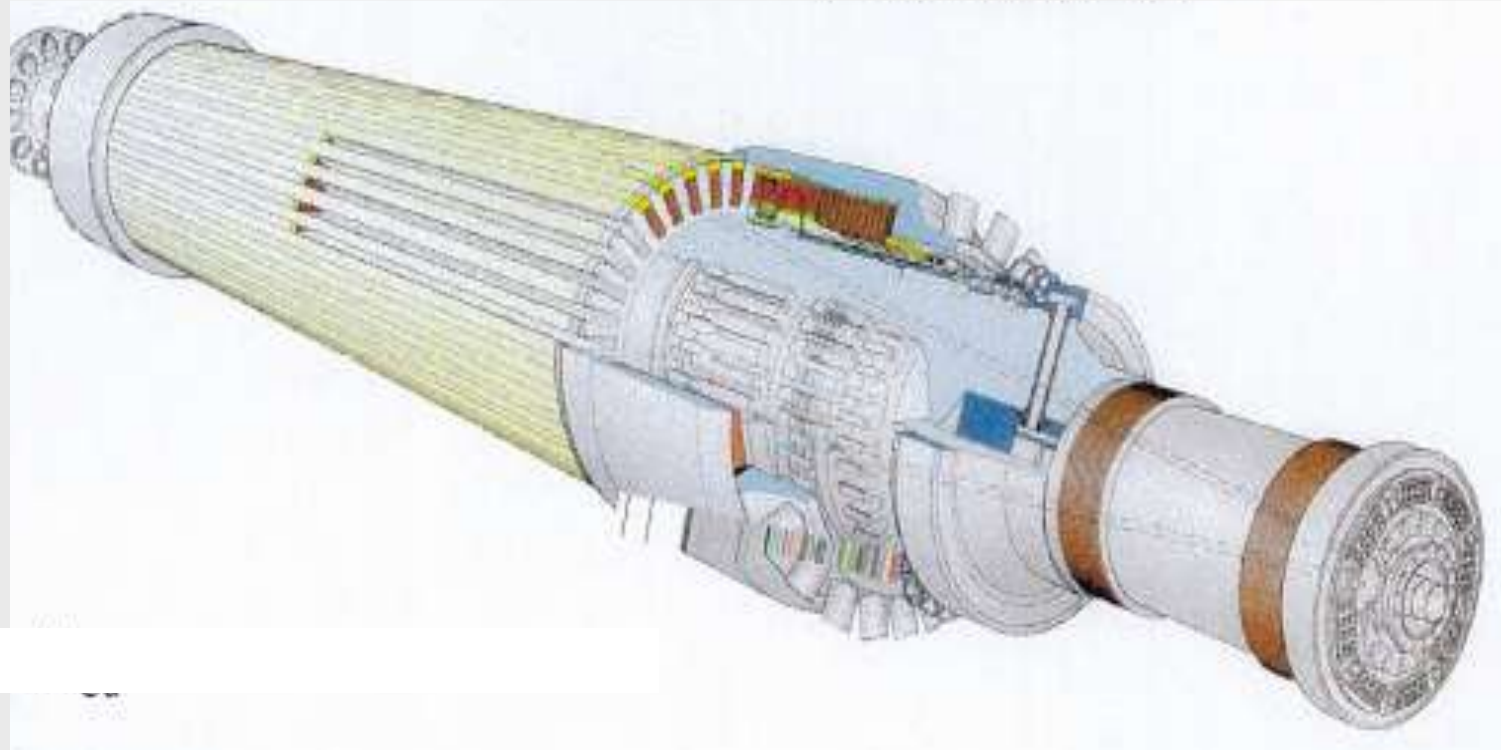


Exciter Side

Vibrations in Generators of Turbogenerators

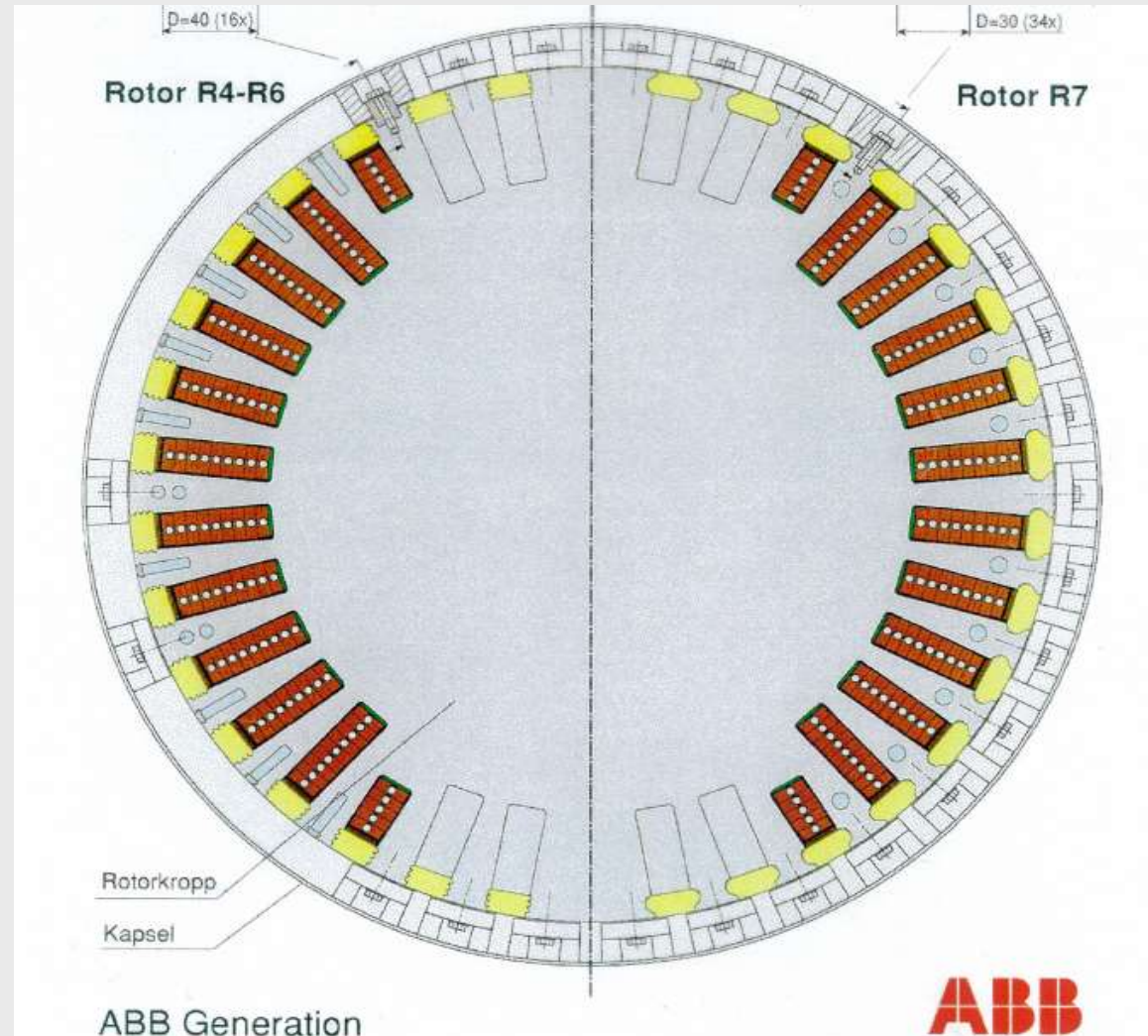
- **Special Vibration Problems in Generators**
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Laval Rotor, unequal moments of inertia Two Pole Generator



Laval Rotor, unequal moments of inertia Two Pole Generator, cross section

IFTtoMM
2006



Laval Rotor, unequal moments of inertia

Different cross sections

Cross
Section

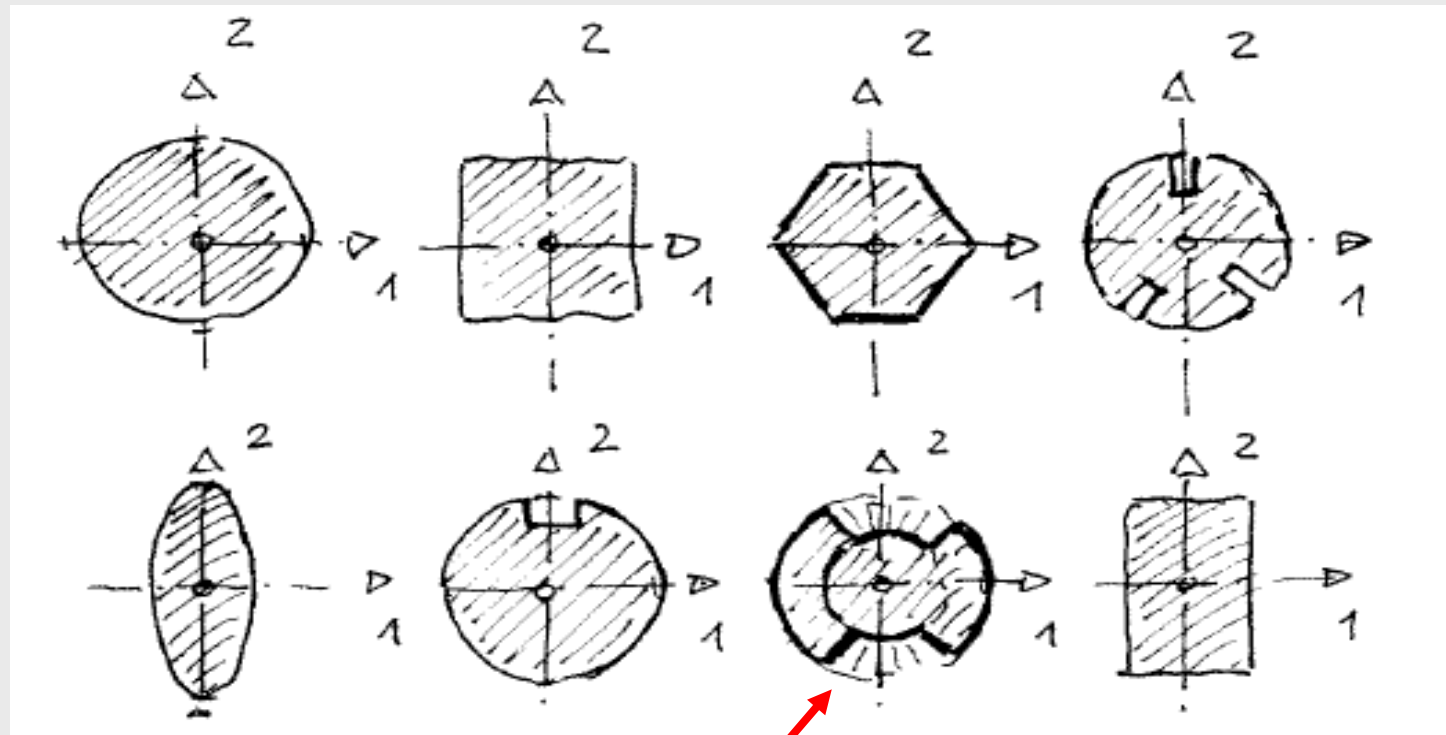
Circular

Quadratic

Hexagonal

With 3 slots

Equal
Moments
of Inertia



Unequal
Moments
of Inertia

Cross
Section

Elliptical

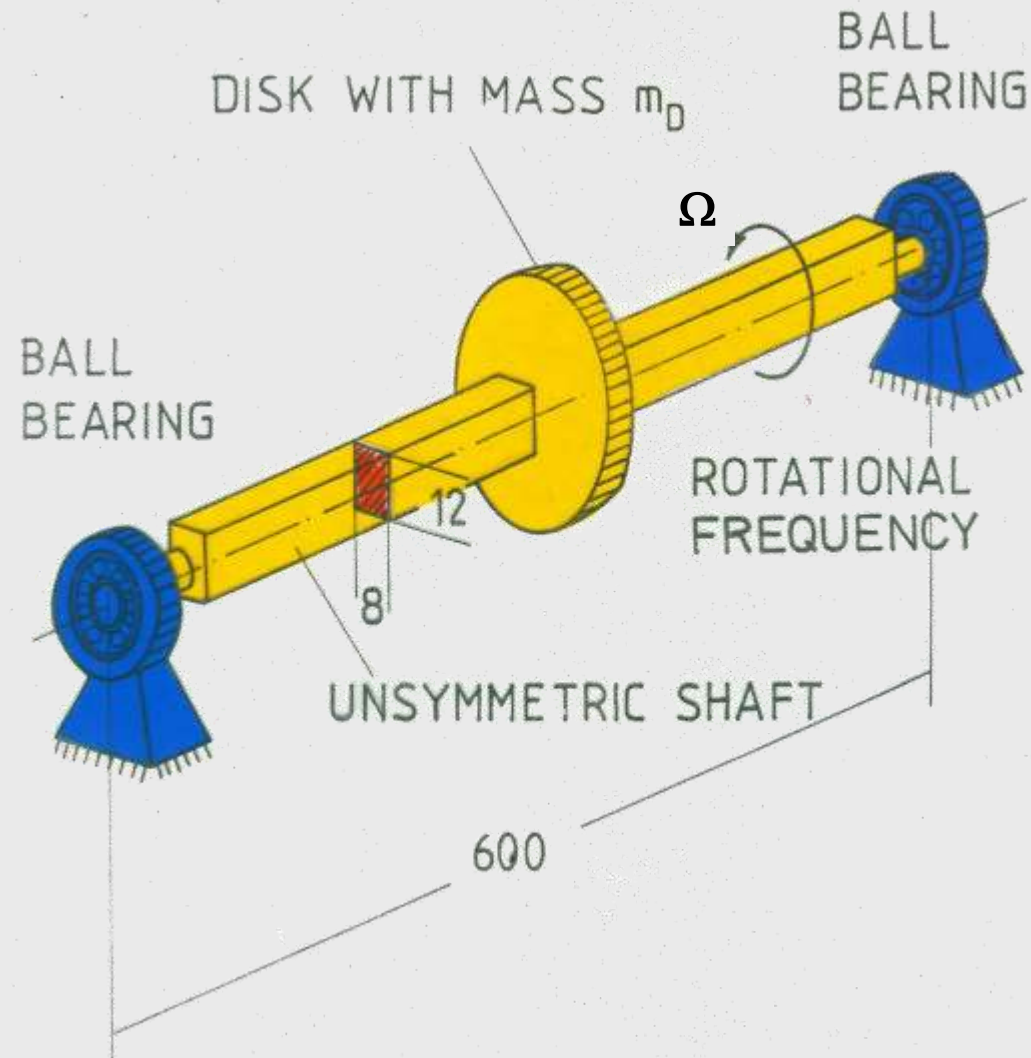
With a
Groove

Two Pole
Generator

Rectangular

Laval Rotor, unequal moments of inertia

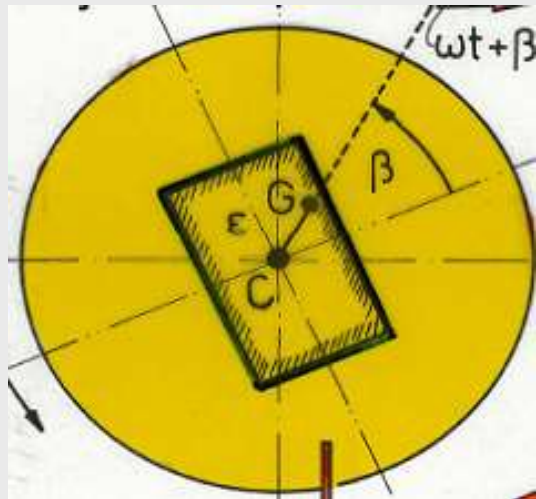
Model of rotor with rectangular cross section



Laval Rotor, unequal moments of inertia

Minimum and maximum Stiffness

Direction of
Maximum
Stiffness k_{max}



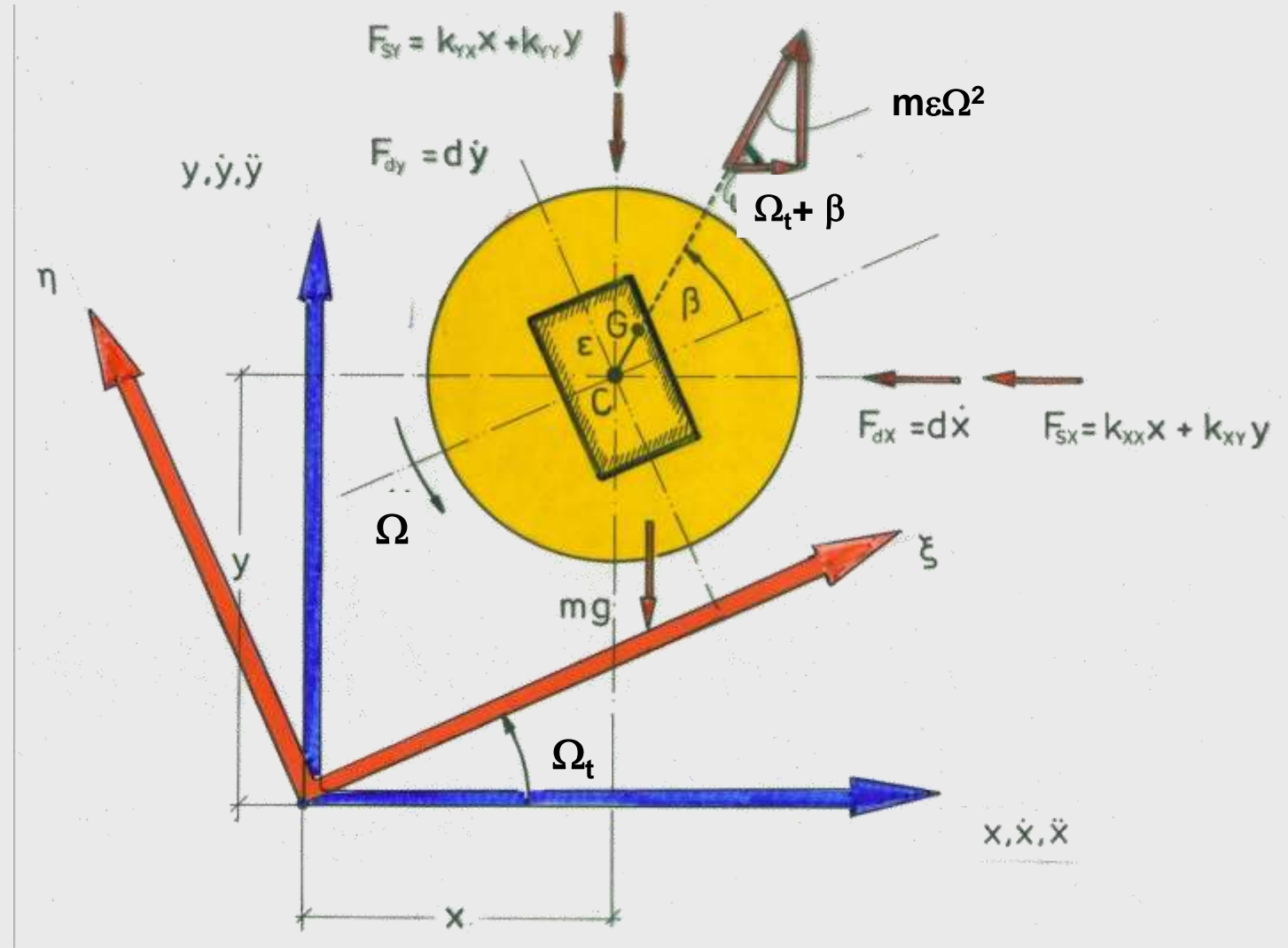
Direction of
Minimum
Stiffness k_{min}

Definition of the
dimensionless
**Inequality of the
Shaft Stiffnesses**

$$u = k_{max} - k_{min} / k_{max} + k_{min}$$

Laval Rotor, unequal moments of inertia

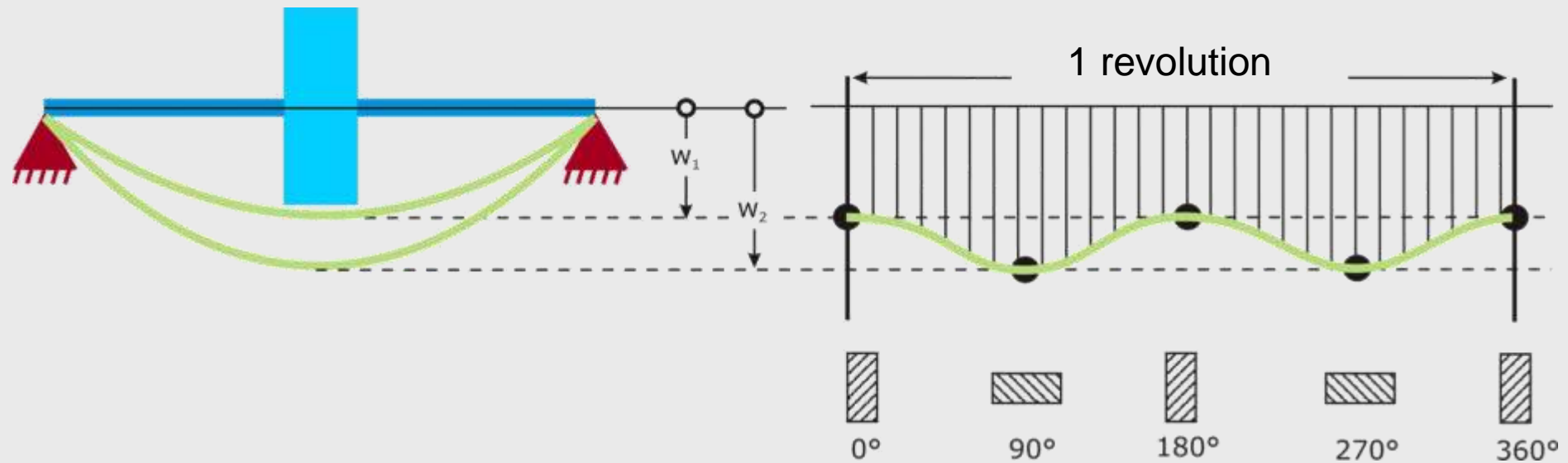
Fixed and rotating coordinate system



Laval Rotor, unequal moments of inertia

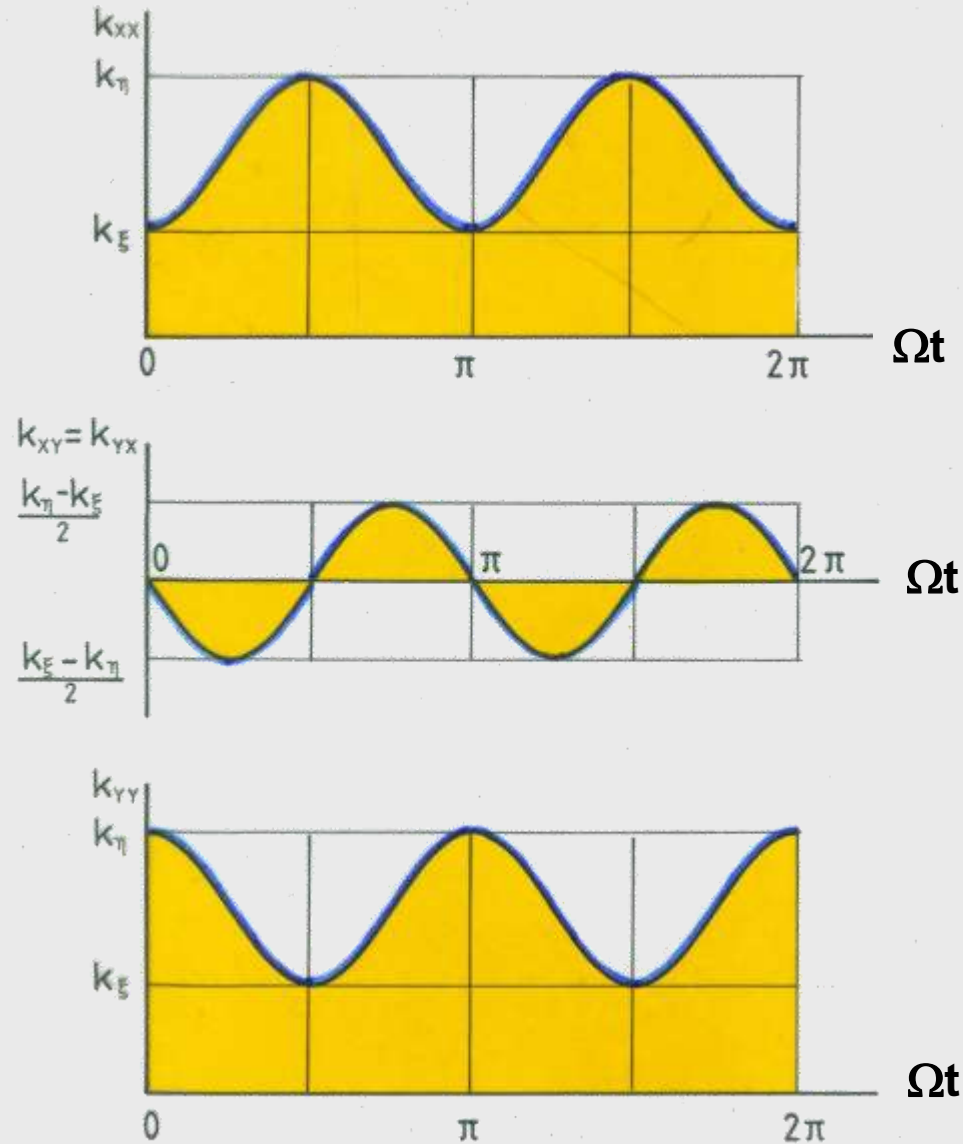
Shaft deflection for one revolution

Weight, lifted twice per revolution



Laval Rotor, unequal moments of inertia

Time dependent shaft stiffness



Laval Rotor, unequal moments of inertia

Equations of motion in fixed coordinate system

$$\begin{bmatrix} m & 0 \\ 0 & m \end{bmatrix} \begin{bmatrix} \ddot{x} \\ \ddot{y} \end{bmatrix} + \begin{bmatrix} d & 0 \\ 0 & d \end{bmatrix} \begin{bmatrix} \dot{x} \\ \dot{y} \end{bmatrix} + \begin{bmatrix} k_{xx} & k_{xy} \\ k_{yx} & k_{yy} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = m\varepsilon \Omega^2 \begin{bmatrix} \cos(\Omega t + \beta) \\ \sin(\Omega t + \beta) \end{bmatrix} + \begin{bmatrix} 0 \\ -mg \end{bmatrix}$$

$$\underline{M}^F \cdot \underline{\ddot{x}} + \underline{D}^F \cdot \underline{\dot{x}} + \underline{K}^F(t) \cdot \underline{x} = \underline{f}_\varepsilon^F(t) + \underline{f}_G^F$$

$$\underline{K}^F(t) = \frac{k_\eta + k_\xi}{2} \cdot \begin{bmatrix} 1 - \mu \cos 2\Omega t & -\mu \sin 2\Omega t \\ -\mu \sin 2\Omega t & 1 + \mu \cos 2\Omega t \end{bmatrix}$$

 k_η, k_ξ

Principal stiffness

$$\mu = \frac{k_\eta - k_\xi}{k_\eta + k_\xi}$$

Dimensionless stiffness inequality

Laval Rotor, unequal moments of inertia

Dynamic Behavior

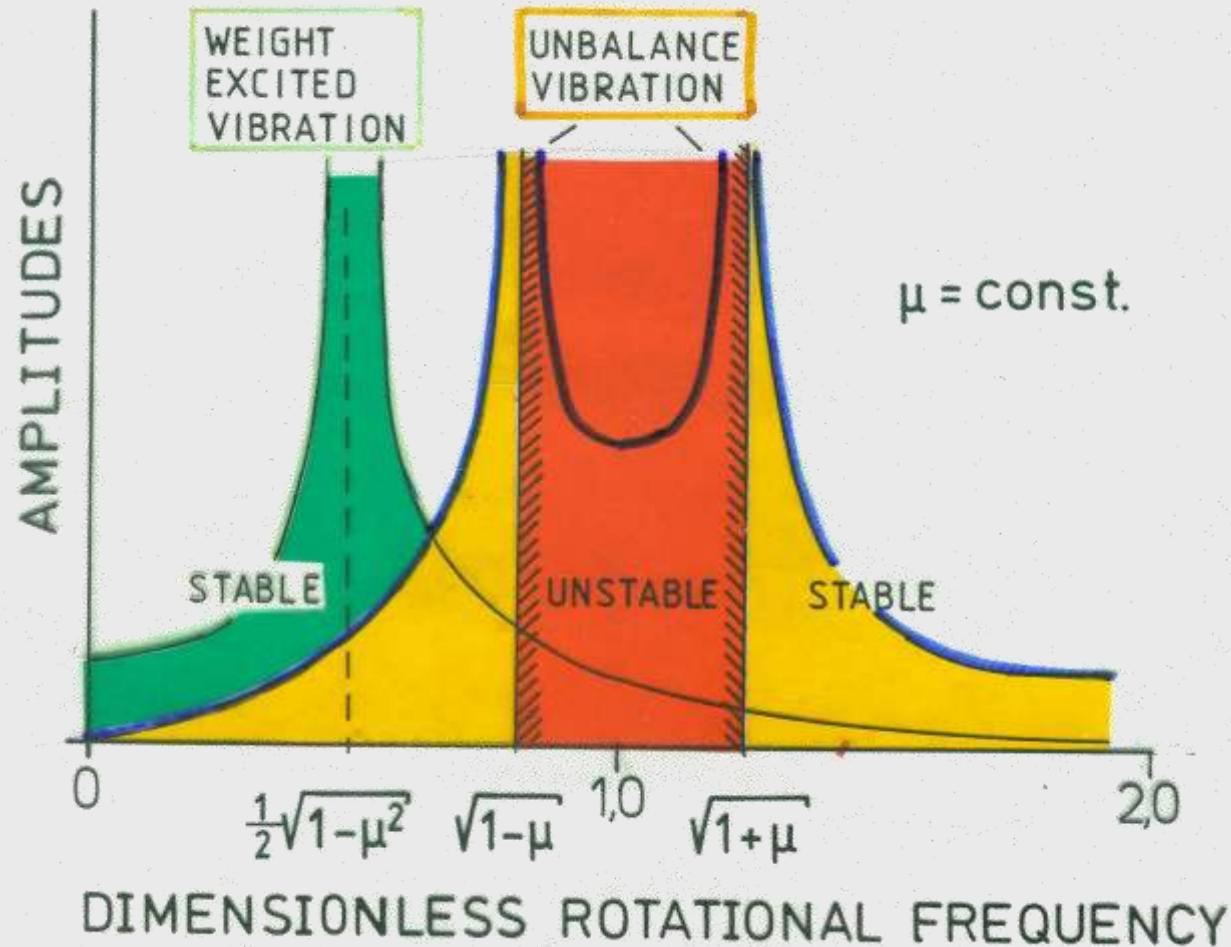
The shaft of the considered Laval Rotor has Unequal Moments of Inertia. Due to the **different stiffnesses** in the two directions we expect **two Natural Frequencies** or **two Critical Speeds** due to Unbalance.

When the shaft rotates the **weight of the disk is lifted two times per revolution**. For the rotational frequency ω a Frequency of excitation 2ω is expected. When this Frequency of excitation is equal to a Natural Frequency of the Laval Rotor the **Weight Resonance** appears.

Between the **two Critical Speeds** instability may occur.

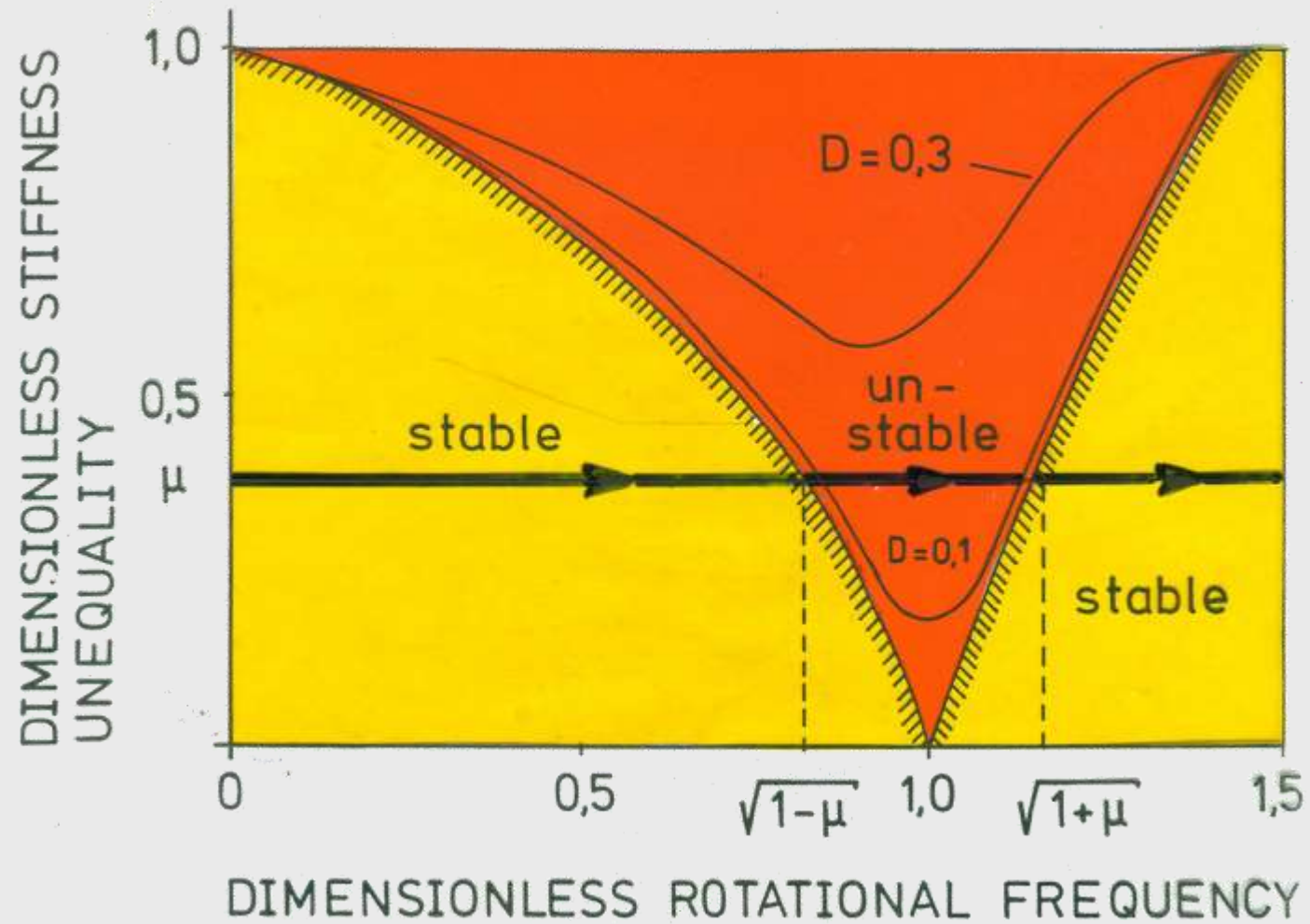
Laval Rotor, unequal moments of inertia

Amplitudes of forced vibrations



Laval Rotor, unequal moments of inertia

Stability map in dependence of damping



Vibrations in Generators of Turbogenerators

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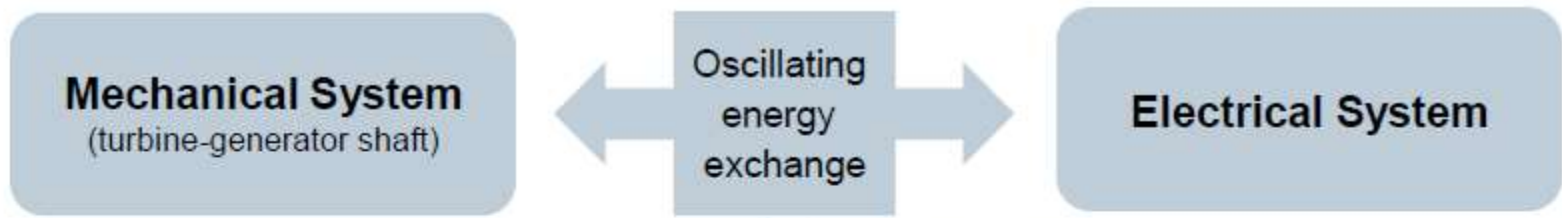
Sub Synchronous Resonance (SSR)

Introduction

Sub Synchronous Resonances are oscillations in the electrical and mechanical systems which occur, when the turbogenerator units feed into a network, the long lines of which are compensated by series capacitors.

An electrical resonant circuit can be triggered by a fault in the electrical system and an exchange of energy can occur between the shaft and the inductive and capacitive elements of the “Generator-Transformer-Line-Network” circuit.

The resulting currents generate low Frequency Electrical Torques in the Generator air gap.



electrical
oscillation =
natural frequency

Mechanical oscillation

N.B.:
Occurance of natural SSR
depends on site-specific
conditions!



Sub-synchronous resonance is an electric power system condition where the electric network exchanges energy with a turbine generator at one or more of the natural frequencies of the combined system below the synchronous frequency of the system.

(IEEE SSR Working Group, "Proposed Terms and Definitions for Subsynchronous Resonance," IEEE Symposium on Countermeasures for Subsynchronous Resonance, IEEE Pub. 81TH0086-9-PWR, 1981,p 92-97.)



Natural frequencies
below the synchronous frequency

If these frequencies are in the vicinity of one of the lowest Natural Torsional frequencies of the shaft line, the shaft assembly may be excited to strong Resonant Vibrations.

These in turn are transmitted into the electrical system by the electromechanical coupling. The electro-mechanical damping of the coupled system may be low or **even negative**.

If the damping is negative, there is an increase in the torsional vibrations and in the electrical torque, which may lead to high stresses and even to damage.

In order to protect the mechanical system of the shaft train against **Sub Synchronous Resonances**, control systems have been developed.

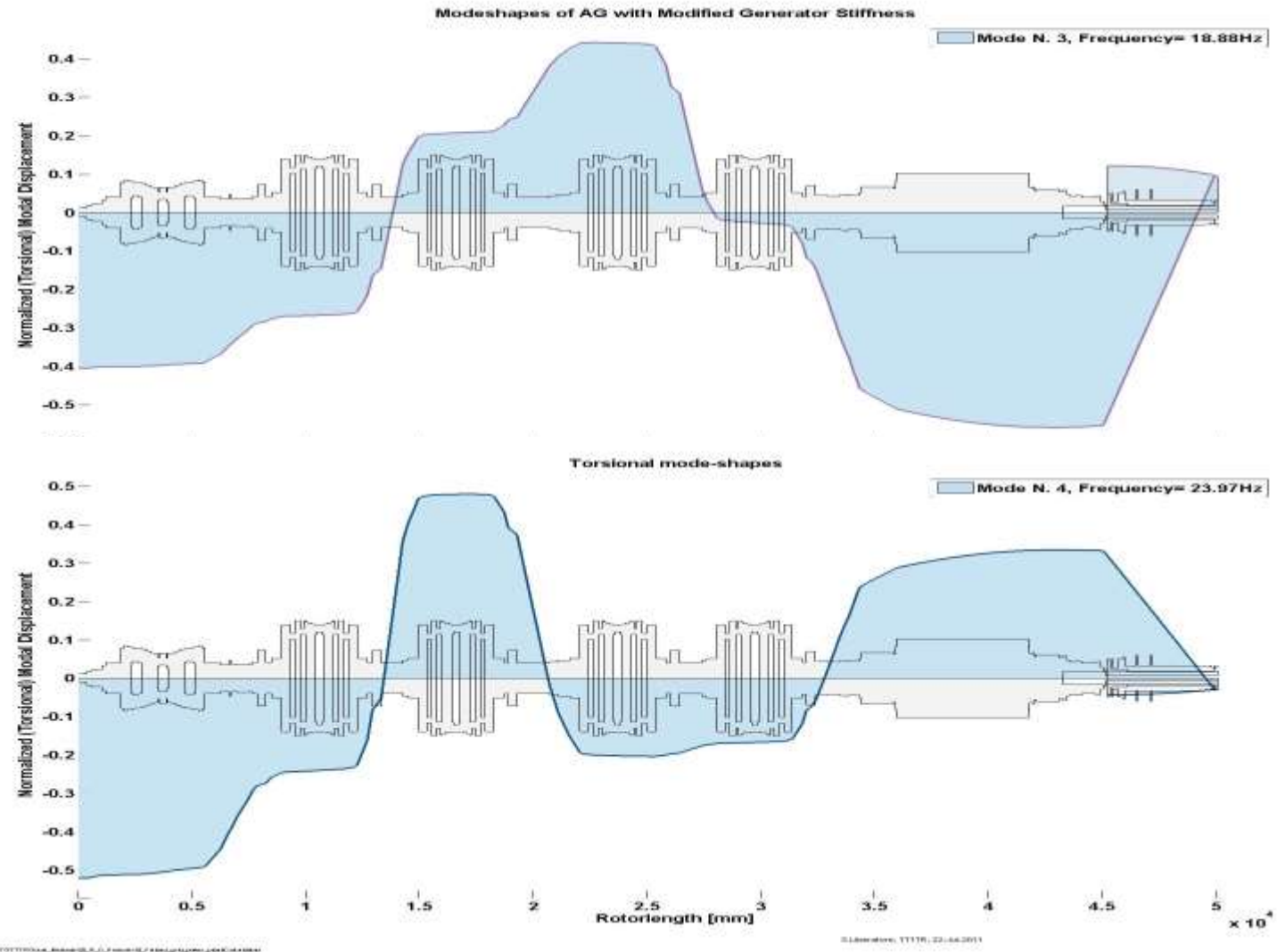
Such control systems need as input data the torsional natural frequencies of the shaft train in the low frequency range (sub synchronous) and in addition the maximum allowable angular displacements of the sub synchronous oscillation modes for the generator angle (measurement location) before any part of the shaft system has reached its fatigue limit.

These numerical data have to be delivered by the manufacturer. As an example the following shows the torsional natural frequencies of the shaft train in a Finish power plant in the low frequency range.

Eigenfrequencies - Modeshapes

Mode N.	Frequency (Hz)	Description of modes
1	7.7	Exciter quill-shaft
2	9.3	Shaft-line 1st (quill-shaft in antiphase)
3	18.9	Shaft-line 2nd (LP3-HP-Gen.)
4	24.0	Shaft-line 3rd (LP2-HP-LP4+Gen.)
5	29.1	LP4-LP3-Gen.
6	35.7	HP-LP1
7	119.3	Exciter 1st mode
8	124.5	Generator 1st mode

Eigenfrequencies - Modeshapes



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